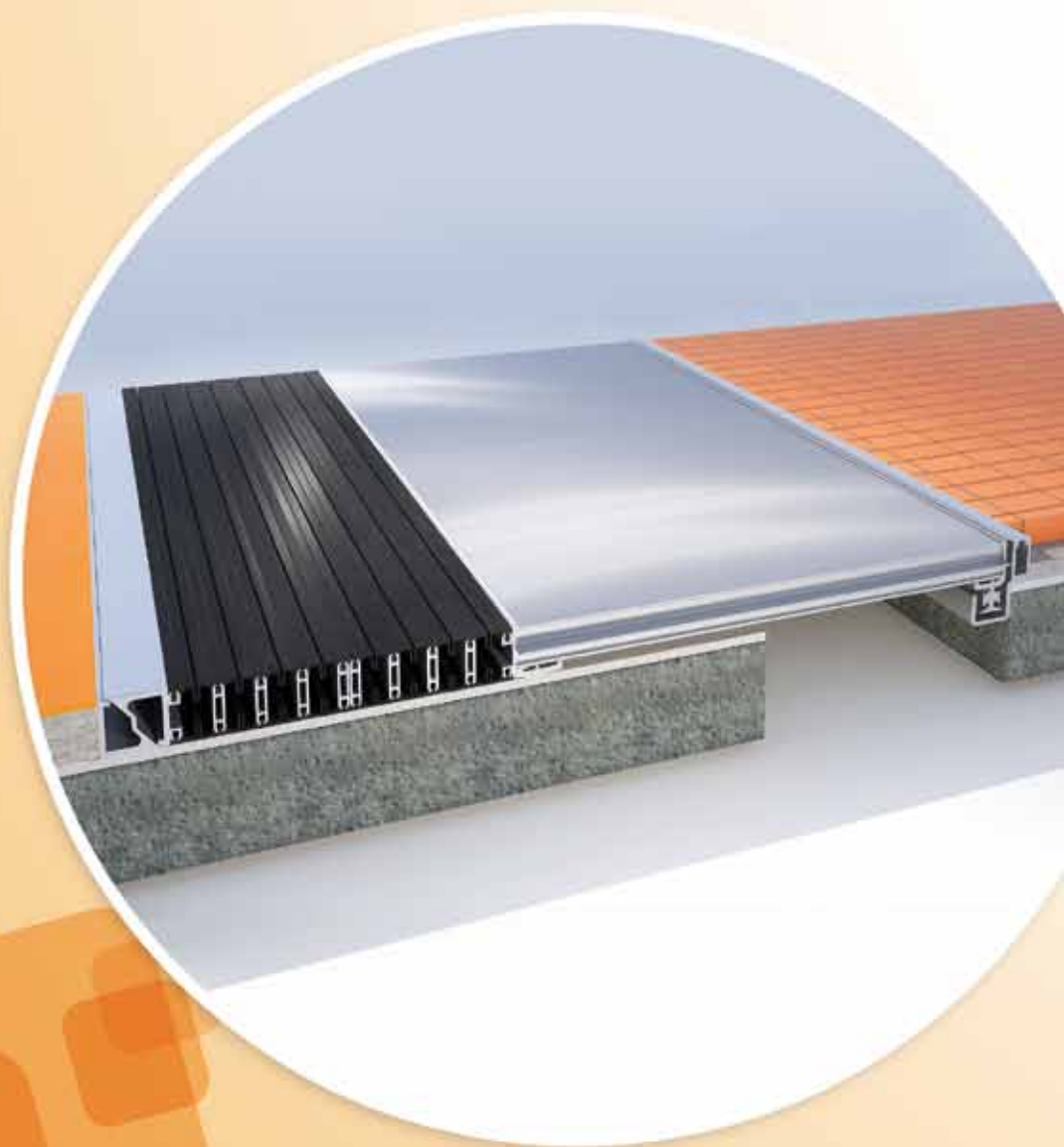




**TECNOKGIUNTI**  
Seismic Joint



# **K 3D** SYSTEM

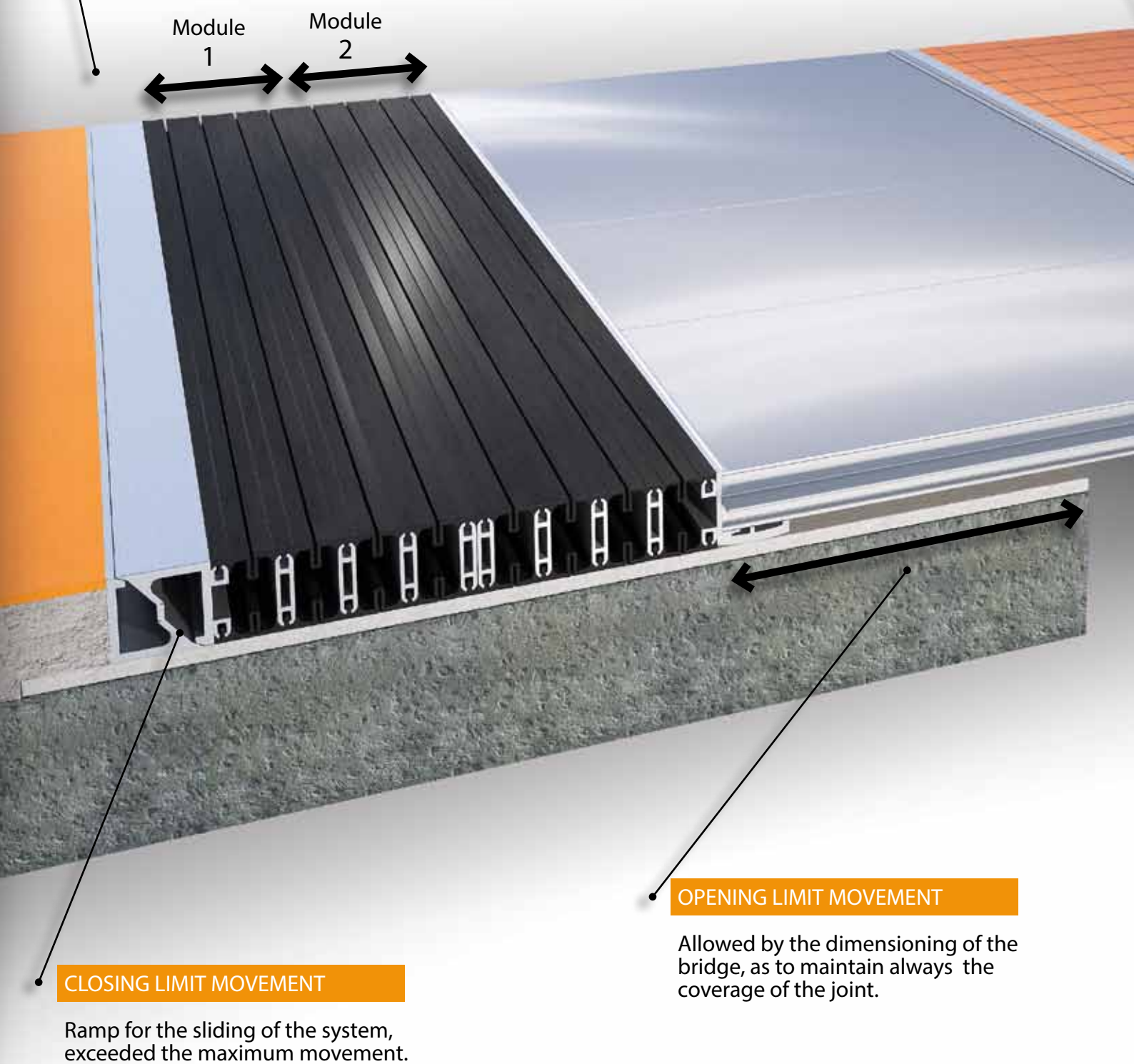
Seismic joint system specially  
designed for base isolated buildings

### TRANSVERSE MOVEMENT

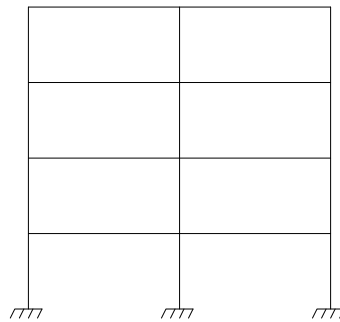
Managed by modules made of reinforced rubber, +/- 100mm of movement each one.

### LONGITUDINAL MOVEMENT

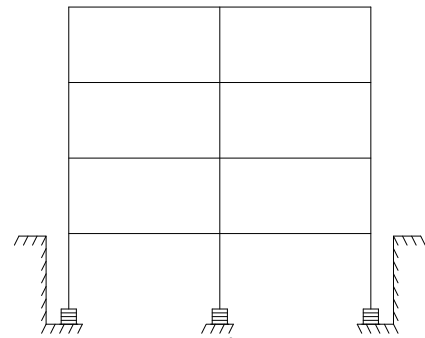
Allowed by the patented sliding trolleys system.



# Seismic joint system specially designed for base isolated buildings



Base traditional



Base isolation

Base isolation is a technique developed to minimise damage to buildings during an earthquake, isolating the structure from potentially dangerous ground motions.

To ensure this advantage is also essential to separate the building from structures adjacent to the entire perimeter by joints larger than the movements expected during the earthquake.

**SEISMIC JOINT COVERS** have a key role to play:

- To ensure the movement in the two directions of the plane equal to the movement of the isolators.
- To avoid seismic pounding between adjacent building structures.
- To cover the expansion joints during movements in order to ensure a safe transit to people along the escape routes.
- To don't allow the collapse of the system or other objects from the joint during the movements.
- To provides a flat surface for a bumpless transit of people, wheelchairs, stretchers and machinery, even during seismic movements.
- Durability, thanks to the use of materials not subject to corrosion or deterioration.

Failure to comply with these requirements may jeopardize the proper functioning of base isolation and make it impossible to use escape routes during and after a seismic event.

## K 3D

Seismic joint system for joints up to 1000 mm subject to high movements up to  $\pm 950$  mm, specially designed for base isolated buildings. Suitable for loads by cars.

The system consists of a rectangular section devoid of underfloor brackets and visible screws. Central plate rigid and antislip, made of knurled aluminium. Gaskets made of rubber with high resistance to vertical loads.

The system supports the movement in 3 directions, a special system of sliding on rollers allows longitudinal movements.

### STRENGTH

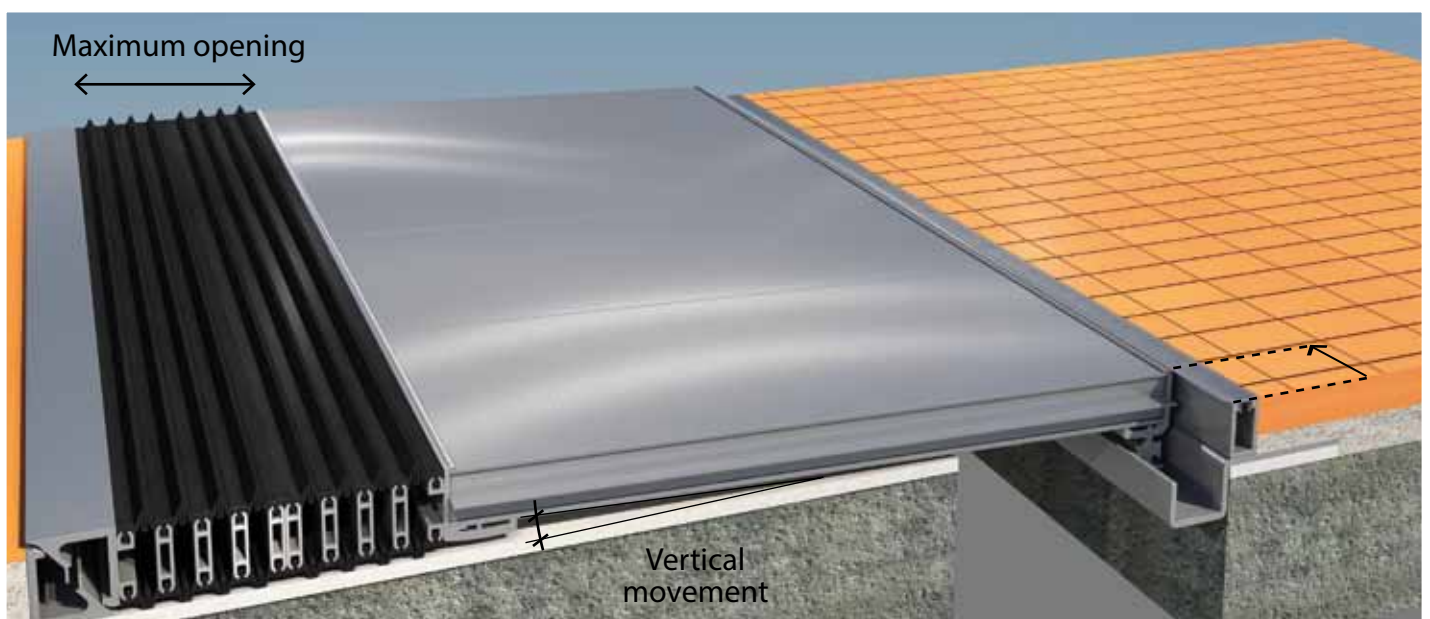
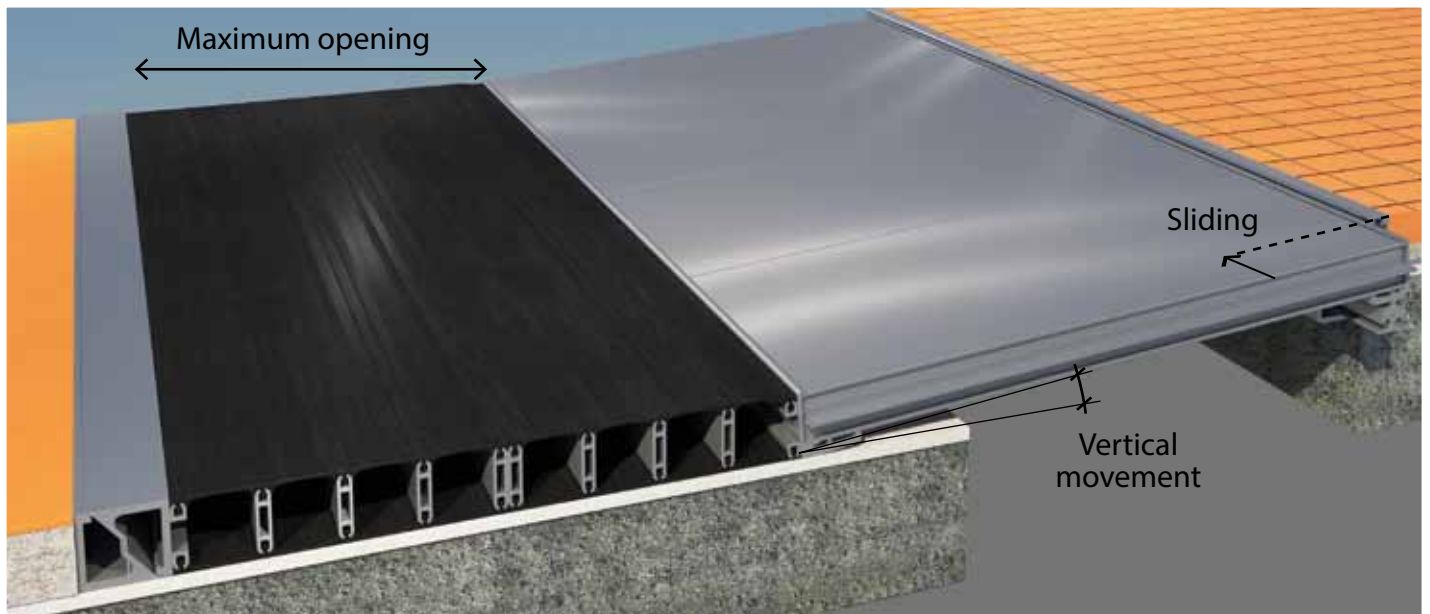
The high-performance central element consists of aluminum I-Beams.



Watch the 3D simulation



# DLS = ULS SIMULATION



# MOVEMENTS

**To mitigate the seismic risk is also:**

- **To safeguard the integrity of the various components of a building structure**, through an appropriate joint dimensioning to avoid seismic pounding.
- **To protect the integrity and / or functionality of non-structural components**, among which the expansion joints in the floor, whose malfunction or collapse in case of earthquake can cause also serious effects, invalidating for example the availability of some passages (escape routes) or even leaving in the floors, the openings in which people, stretchers or wheelchairs can find obstacle to escape.

An estimate of the width of the joint to be considered “significant” may be made, for example, noting that safety legislation considers a dangerous gap with width over 20 cm, and therefore to be protected. About the above, recent legislation it has provided some indication rather accurate. Referring in particular to the DM 14.1.2008 and 6.5.2008, the very definition of the limit state DLS (Damage Limit State) and OLS (Operational Limit State) refers to the behavior of “non-structural parts.” It requires, for example, that at the DLS the building as a whole, including the non-structural elements, “must not be damaged and must be operational” or “be damaged such as not to endanger the users” remaining immediately usable, despite the interruption of the usability of part of the devices

## *extracts of standards*

“(NTC 2008: 7.2.3): “With the exception of interior infill walls [...], the non-structural elements, which if disrupted, can cause damage to people [...] must be verified for the seismic action corresponding to each limit state considered”

The expansion joint systems must be able to allow the movements OLS, without suffering no damage during the earthquake, during the movements DLS there must be no falls of components during earthquake and, out of this; the passage should be still accessible.

the jointing systems are therefore an integral part of life and the level of security of any major structure, obviously with particular reference to seismically isolated and in the public and strategic buildings, such as hospitals, schools, shopping centers and large production buildings.

The design of systems TECNOK JOINTS, entirely Italian, takes full account of these legislative parameters, respectively accounting for the fulfillment of the DLS and ULS (ultimate Limit State) through specific “thermal motion”, “seismic movement” and “last movement.”

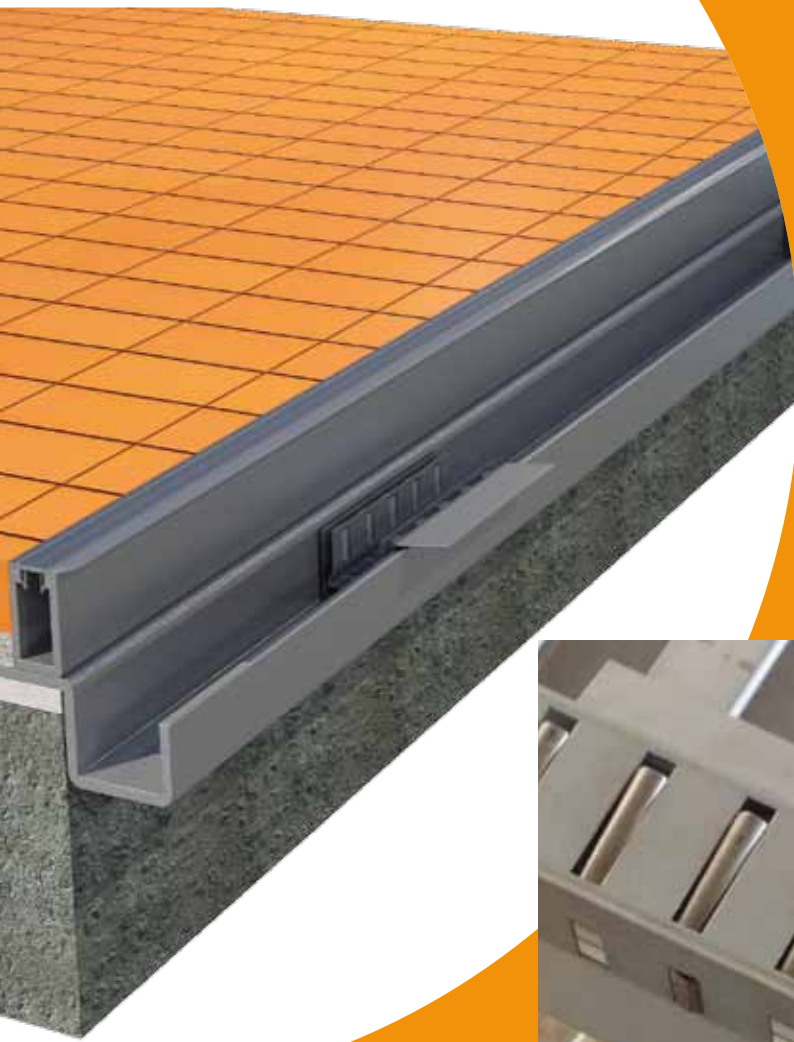
The K-Series 3D finally, provides the fulfillment of the most stringent specifications, typical for example of the isolated structures, also thanks to the possibility of compensating movements in both directions of the plane.

**The joint systems must meet specific performance specifications of design and usability movement, directly related to the different limit states project:  
there is less and less room for improvisation**

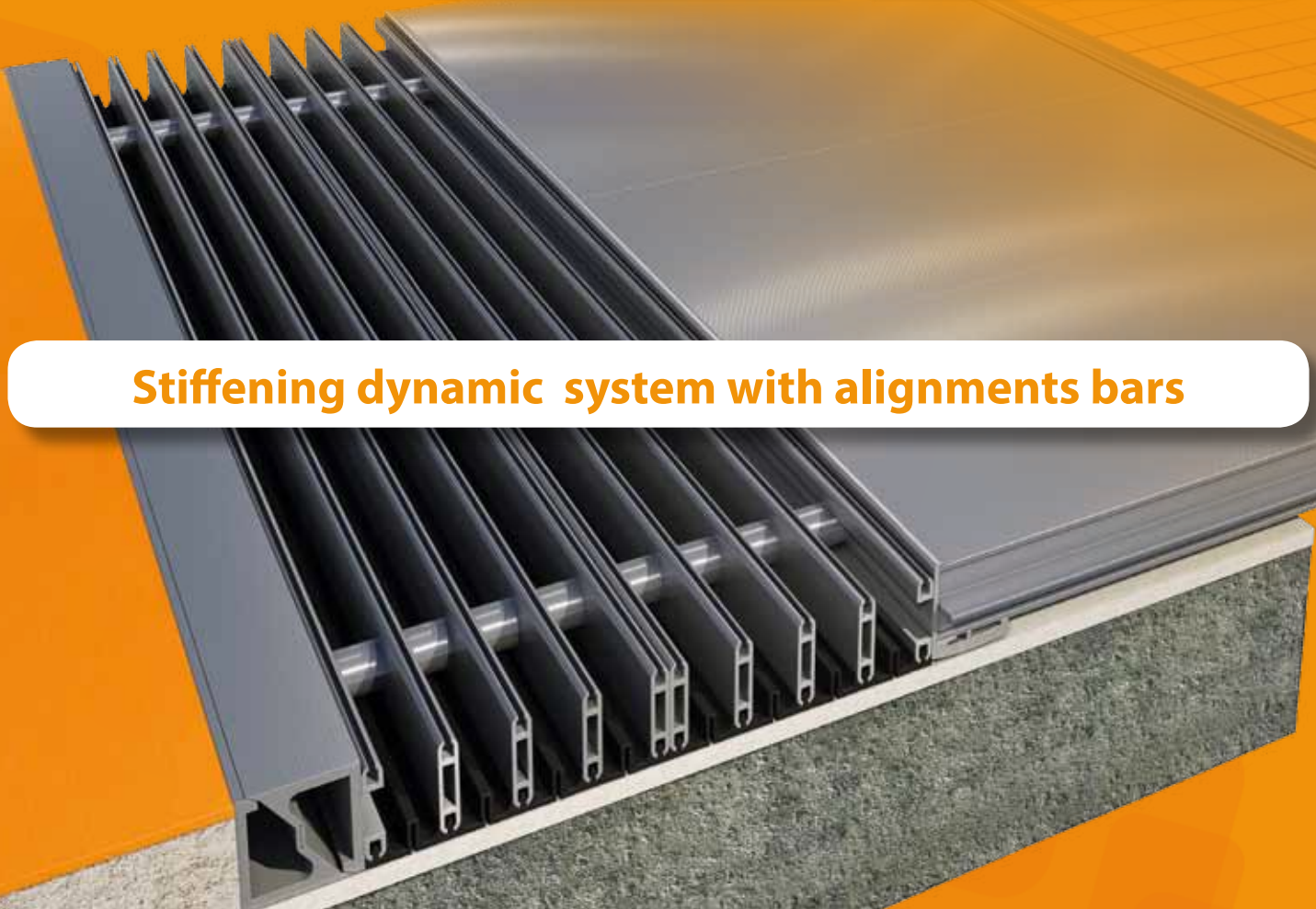


# MOVEMENTS DETAIL

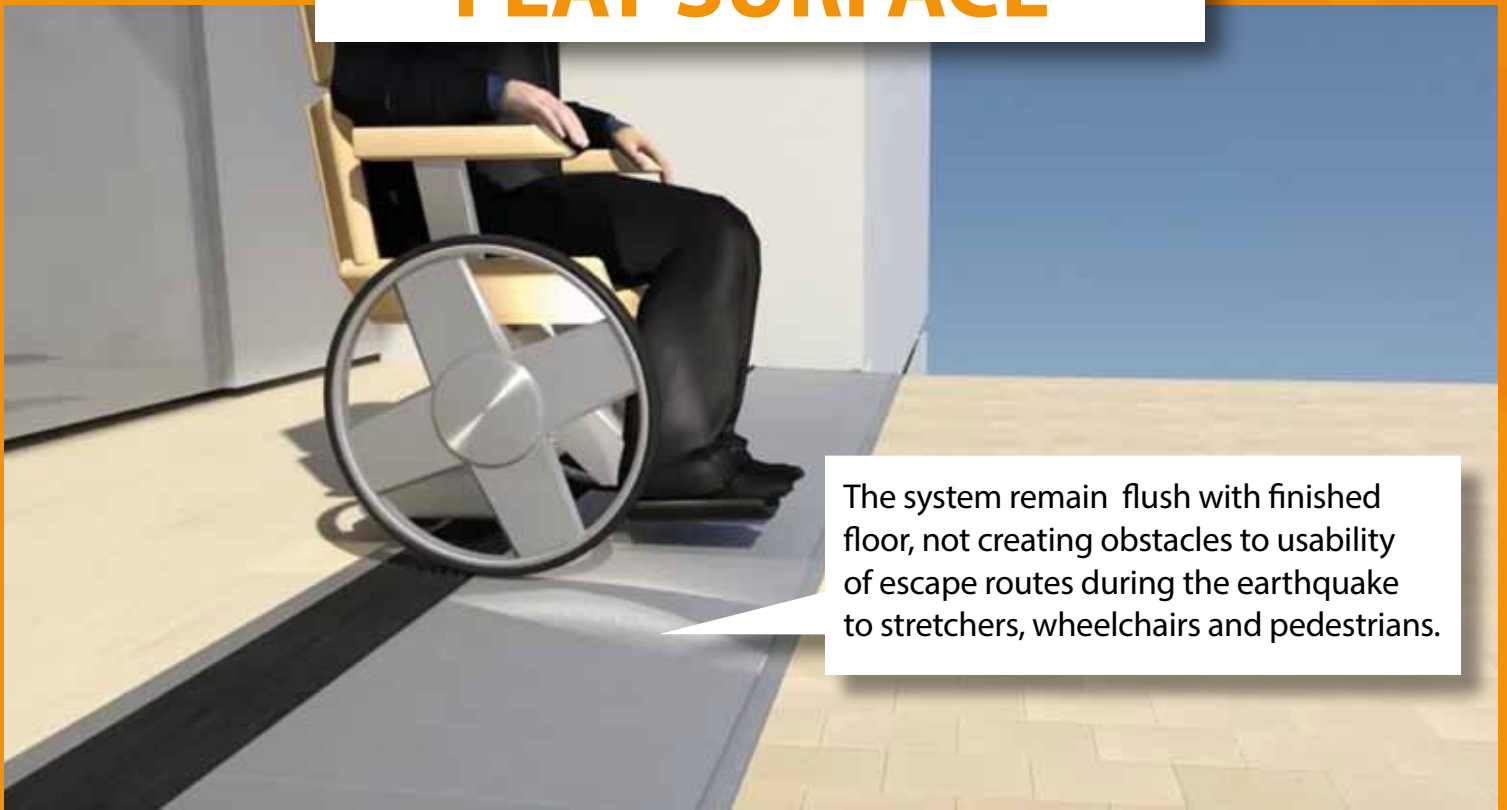
patented sliding  
trolleys system with  
cylindrical bearings



**Stiffening dynamic system with alignments bars**



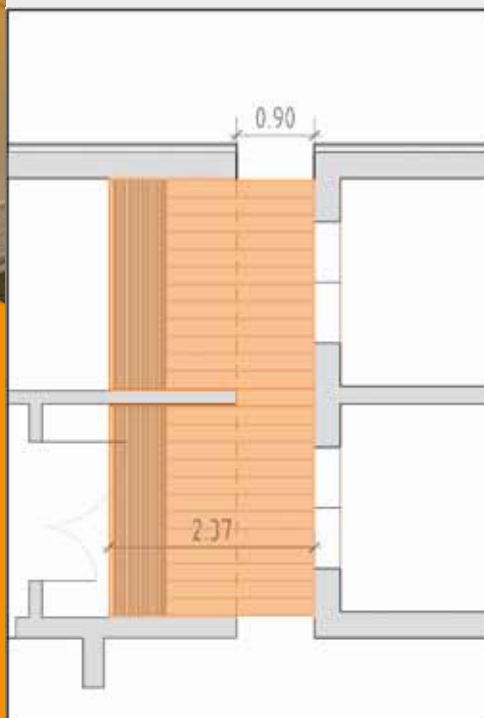
# FLAT SURFACE



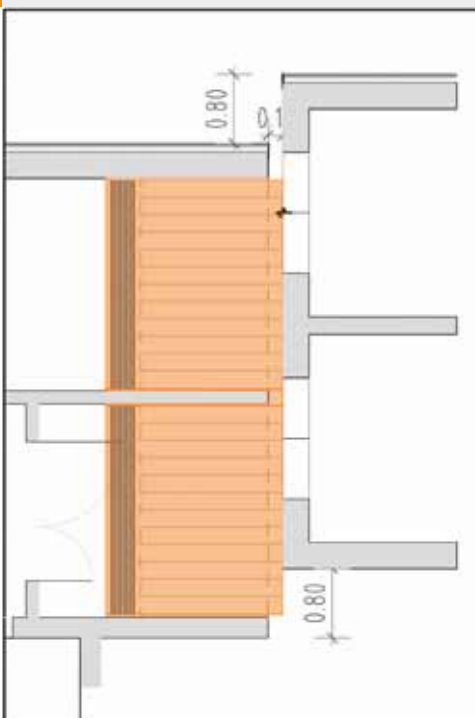
# SEISMIC POUNDING

The system (as represented in the drawing) thanks to the positioning of the central bridge, cantilevered into the joint, manages all the longitudinal movements by scrolling to the left of the columns and the adjacent walls, thus making indefinite the movement capability relative. The elastic resistance of the rubber seals do not affect the structural calculation of the structures connected with the system K3D. The gaskets exceeded the movement competent, it is disengaged allowing the vehicle to slide transversely to the joint

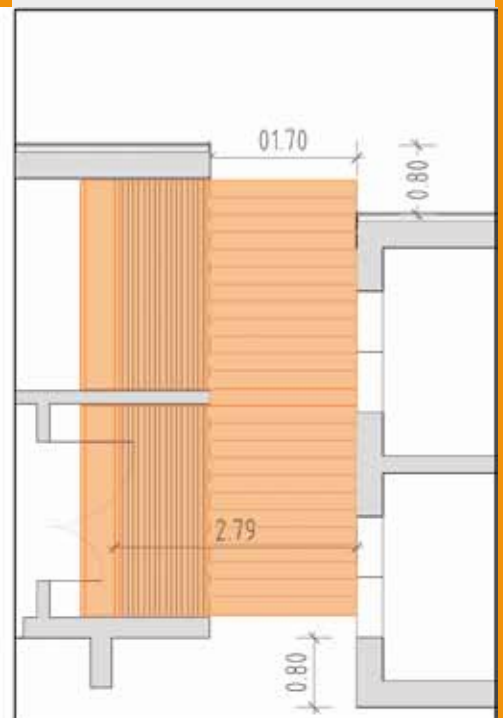
Standard position



- Transverse movement - 800mm
- ↕ Longitudinal movement - 800mm



- Transverse movement - 800mm
- ↕ Longitudinal movement - 800mm



Tipo	G	L	Mov. SLD	Mov. SLU
	mm	mm	mm	mm
K 3D G100 M50	100	325	+/- 50	+/- 50
K 3D G150 M100	150	495	+/- 100	+/- 100
K 3D G200 M100	200	545	+/- 100	+/- 100
K 3D G200 M150	200	675	+/- 150	+/- 150
K 3D G250 M100	250	595	+/- 100	+/- 100
K 3D G250 M100 U200	250	695	+/- 100	+/- 200
K 3D G250 M200	250	845	+/- 200	+/- 200
K 3D G300 M100	300	645	+/- 100	+/- 100
K 3D G300 M100 U250	300	795	+/- 100	+/- 250
K 3D G300 M250	300	1025	+/- 250	+/- 250
K 3D G350 M100	350	695	+/- 100	+/- 100
K 3D G350 M100 U300	350	895	+/- 100	+/- 300
K 3D G350 M200 U300	350	1045	+/- 200	+/- 300
K 3D G350 M300	350	1195	+/- 300	+/- 300
K 3D G400 M100	400	745	+/- 100	+/- 100
K 3D G400 M100 U350	400	995	+/- 100	+/- 350
K 3D G400 M200 U350	400	1145	+/- 200	+/- 350
K 3D G400 M300	400	1245	+/- 300	+/- 300
K 3D G400 M300 U350	400	1295	+/- 300	+/- 350

Tipo	G	L	Mov. SLD	Mov. SLU
	mm	mm	mm	mm
K 3D G450 M100	450	795	+/- 100	+/- 100
K 3D G450 M100 U400	450	1095	+/- 100	+/- 400
K 3D G450 M200 U400	450	1245	+/- 200	+/- 400
K 3D G450 M300	450	1295	+/- 300	+/- 300
K 3D G450 M300 U400	450	1395	+/- 300	+/- 400
K 3D G500 M100	500	845	+/- 100	+/- 100
K 3D G500 M100 U450	500	1195	+/- 100	+/- 450
K 3D G500 M200 U450	500	1345	+/- 200	+/- 450
K 3D G500 M300 U450	500	1495	+/- 300	+/- 450
K 3D G600 M200	600	1195	+/- 200	+/- 200
K 3D G600 M200 U550	600	1545	+/- 200	+/- 550
K 3D G600 M300 U550	600	1695	+/- 300	+/- 550
K 3D G700 M300	700	1545	+/- 300	+/- 300
K 3D G700 M300 U650	700	1895	+/- 300	+/- 650
K 3D G800 M300	800	1645	+/- 300	+/- 300
K 3D G800 M300 U750	800	2095	+/- 300	+/- 750
K 3D G900 M300	900	1745	+/- 300	+/- 300
K 3D G900 M300 U850	900	2295	+/- 300	+/- 850
K 3D G1000 M300	1000	1845	+/- 300	+/- 300
K 3D G1000 M300 U950	1000	2495	+/- 300	+/- 950

The table shows only some examples, consult our technical department for intermediate cases.

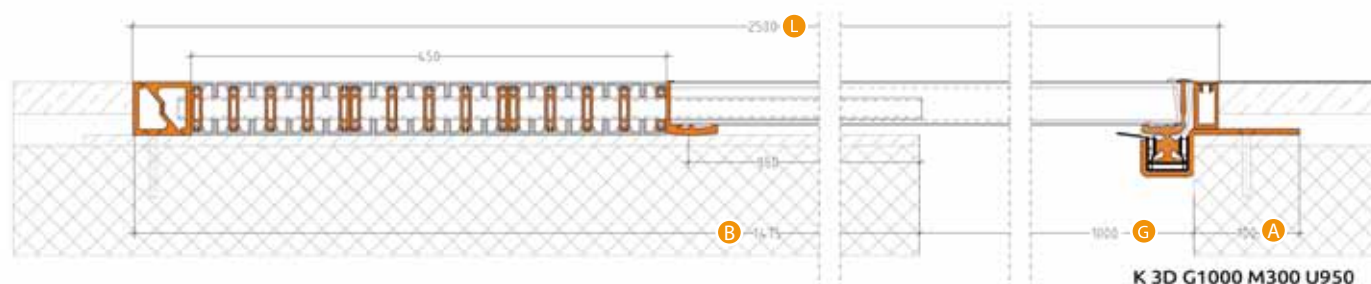
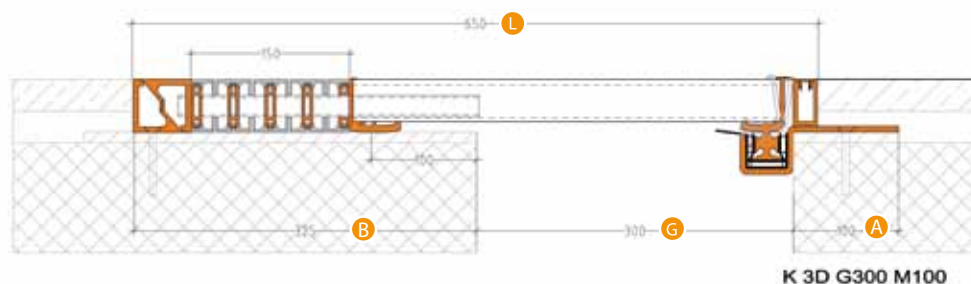
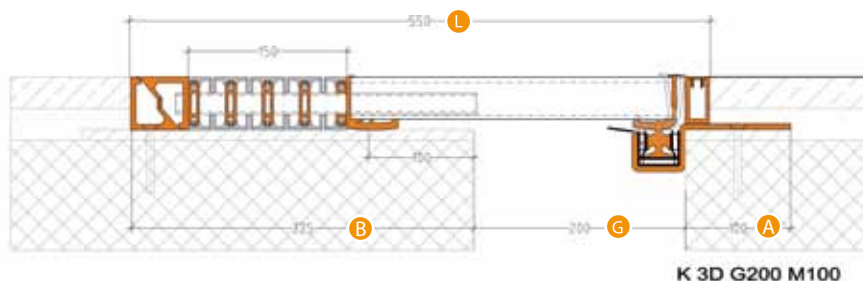
## Dimensions:

**A** = Laying surface lower = 100

**B** = Laying surface major = 70+ **U** (M if absent U) + 150 (for each module M 100 mm) + 80 (for each module M 50 mm)

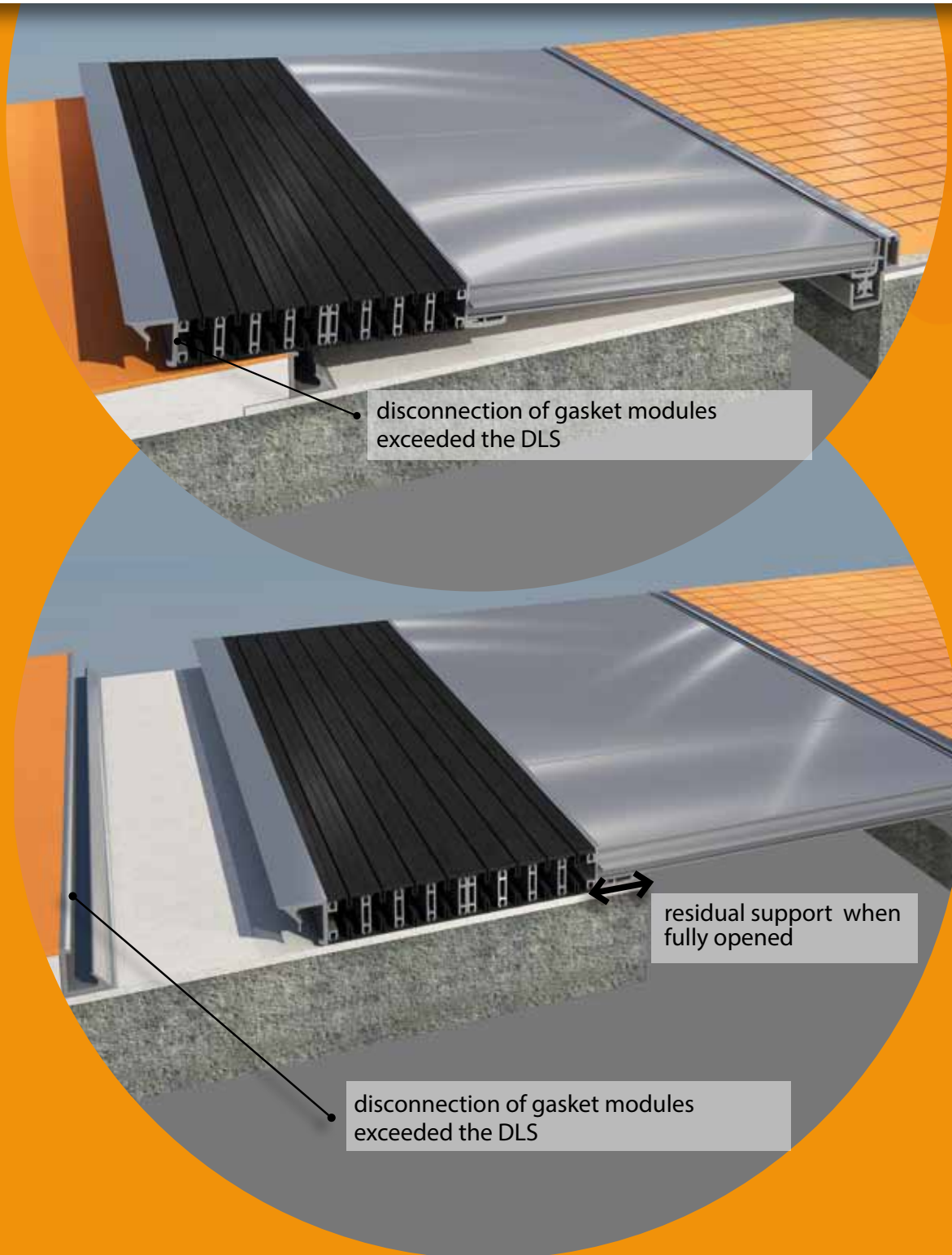
**L** = B + G + 25

**Ltot** = Overall dimensions = B + G + A





# ULS > DLS SIMULATION



The movements to the DLS (Damage limitation state) are handled by the system gaskets, always guaranteeing a smooth transition surface without hindrance.

Exceeded these movements the system is designed to continue to ensure, however, the coverage of the gap (preventing things and people from falling into the gap) and the Free movement of the structures, up to the ULS (ULTIMATE LIMIT STATE).

As it can be seen from the drawings, in the closing phase the system goes up the inclined ramp to slide on the adjacent flooring. In the opening phase the system runs on the laying surface, of sufficient amplitude to guarantee the support a planar surface.

SO it IS ALWAYS BETTER TO CHOOSE THE SYSTEM WITH DLS COINCIDING WITH ULS to guarantee the flatness of the escape routes.

# FIRE PROTECTION

The seismic joint K3D can be equipped with fire system K FIRE PAD for joints width of up to 1.2 m. The system is fixed to the two sides of the structure and can be sized in such a way as to guarantee the expected movements. Returned to the standard position will again be able to guarantee resistance EI 120 or EI 180 as requested.

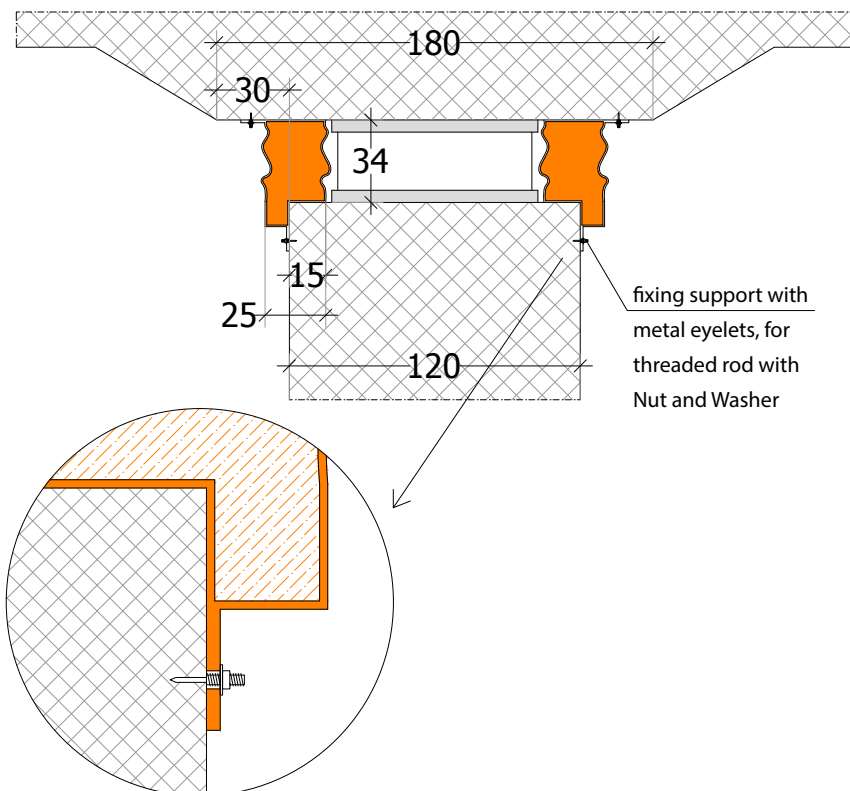


## Application example on isolators

### K FIRE PAD 600

- for joints between pillar and floor
- joint nominal width 350 mm
- total movement required 500 mm (+/- 250 mm)
- EI 120

The system is made of a single piece long enough to cover the four sides of the pillar



The K FIRE PAD, certified according to UNI EN 1366-4: 2010 with characteristics EI 120 or EI 180, also allows the protection of the seismic isolators guaranteeing the effectiveness even after the movements caused by the earthquake..







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